

1 **Estimating sampling error of evolutionary statistics based on**
2 **genetic covariance matrices using maximum likelihood**

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19

20 **Abstract**

21 We explore the estimation of uncertainty in evolutionary parameters using a recently devised
22 approach for resampling entire additive genetic variance-covariance matrices (**G**). Large sample
23 theory shows that maximum likelihood estimates (including restricted maximum likelihood,
24 REML) asymptotically have a multivariate normal distribution, with covariance matrix derived
25 from the inverse of the information matrix, and mean equal to the estimated **G**. This suggests
26 that sampling estimates of **G** from this distribution can be used to assess the variability of
27 estimates of **G**, and of functions of **G**. We refer to this as the REML-MVN method. This has
28 been implemented in the mixed model program Wombat. Estimates of sampling variances from
29 REML-MVN were compared to those from the parametric bootstrap and from a Bayesian
30 Markov chain Monte Carlo (MCMC) approach (implemented in the R package MCMCglmm).
31 We apply each approach to evolvability statistics previously estimated for a large, 20-
32 dimensional data set for *Drosophila* wings. REML-MVN and MCMC sampling variances are
33 close to those estimated with the parametric bootstrap. Both slightly underestimate the error in
34 the best-estimated aspects of the **G** matrix. REML analysis supports the previous conclusion that
35 the **G** matrix for this population is full-rank. REML-MVN is computationally very efficient,
36 making it an attractive alternative to both data resampling and MCMC approaches to assessing
37 confidence in parameters of evolutionary interest.

38

39 **Keywords:** G matrix, quantitative genetics, evolution, restricted maximum likelihood,
40 evolvability, sampling error

41 Introduction

42 The evolutionary properties of sets of phenotypic traits in outbred populations are summarized
43 by the additive genetic variance-covariance matrix, \mathbf{G} (Lande, 1979). When paired with an
44 estimate of the strength and direction of selection, \mathbf{G} predicts the rate and direction of evolution.
45 As a result, \mathbf{G} matrix estimates are essential elements in a wide variety of evolutionary statistics
46 that quantify such features as the ability of a population to respond to directional selection on
47 multiple traits (Lande, 1979, Cheverud, 1996, Hansen & Houle, 2008), the degree of modular
48 structure to variation, and how variation of evolution is spread across phenotypic dimensions
49 (Mezey & Houle, 2005, Hine & Blows, 2006, Kirkpatrick, 2009, Houle & Fierst, 2013). A
50 related set of methods focuses on comparison of the evolutionary potential of different
51 populations (Kirkpatrick, 2009, Cheverud, 1996, Cheverud & Marroig, 2007, Krzanowski, 1979,
52 Houle & Fierst, 2013, Hansen & Houle, 2008, Aguirre et al., 2014, Hine et al., 2009).

53 While calculating estimates of such statistics is straightforward, assessing the sampling
54 properties of these statistics is much more challenging. The first step is always to identify a set of
55 \mathbf{G} matrices consistent with sampling variation of the original data. Once this is done, the
56 sampling variation of functions of \mathbf{G} can then be estimated by applying the function to these
57 sample matrices. For many years, data resampling methods, such as bootstrapping or jackknifing
58 (e.g., Phillips & Arnold, 1999, Mezey & Houle, 2005, Hine et al., 2009) have been the major tool
59 for generating such families of estimates. Since estimation of \mathbf{G} matrices is generally
60 computationally demanding, data resampling can be prohibitively time-consuming. The rise of
61 numerical Bayesian estimation using Markov chain Monte Carlo (MCMC) methods (Gelman et
62 al., 2013, Hadfield, 2010) and their increasing application to quantitative genetics (Sorensen &
63 Gianola, 2002, O'Hara et al., 2008, Ovaskainen et al., 2008, Aguirre et al., 2014, Stinchcombe et

64 al., 2014) has provided a simpler general route to the assessment of the uncertainty in
65 evolutionary characteristics. In MCMC methods, the estimation of a \mathbf{G} matrix proceeds by
66 estimating the distribution of \mathbf{G} matrices consistent with the data. The samples from this
67 posterior distribution are then used to estimate variation in evolutionary statistics (e.g. Aguirre et
68 al. 2014). MCMC approaches can also be computationally demanding, and therefore difficult to
69 apply to data sets with large numbers of parameters and large sample sizes.

70 Meyer and Houle (2013) recently proposed an alternative method for sampling entire \mathbf{G}
71 matrices based on Restricted Maximum Likelihood (REML). Provided large sample theory
72 holds, the sampling distribution of the parameters of \mathbf{G} approaches a multivariate normal
73 distribution with covariance matrix given by the inverse of the information matrix. Values of \mathbf{G}
74 can be readily sampled from this distribution. This approach has been implemented in the mixed
75 model program Wombat (Meyer, 2010-2015). We call this the REML-MVN method. A similar
76 general approach has been suggested by Mandel (2013). Meyer & Houle (2013) compared
77 estimates of sampling variances from REML-MVN with those based on simulated data drawn
78 from the same distribution, and obtained close agreement. They showed that confidence
79 intervals from REML-MVN were more accurate than those based on the Delta method (Oehlert,
80 1992) for parameters near their boundaries, such as genetic correlations approaching unity.
81 Kingsolver et al. (2015) used REML-MVN to estimate variation in decompositions of \mathbf{G} for
82 function-valued traits.

83 In this contribution, we demonstrate estimation of evolutionary statistics using REML-
84 MVN for data from a large, high-dimensional data set on wing shape variation in *Drosophila*
85 *melanogaster* (Mezey & Houle, 2005). Hansen and Houle (2008) previously estimated measures
86 of evolvability for these data. The addition of confidence limits to their analysis allows us to

87 assess the robustness of their conclusions. We compare these error estimates to those estimated
 88 using the parametric bootstrap and MCMC.

89 ***Sampling G matrices based on REML estimates***

90 The Restricted Maximum Likelihood multivariate normal (REML-MVN) sampling approach
 91 relies on the result that the distribution of maximum likelihood estimates asymptotically
 92 approaches a multivariate normal distribution as sample size increases. Let $\boldsymbol{\theta}$ denote the vector of
 93 parameters to be estimated, e.g. the $k(k + 1)/2$ distinct elements of a covariance matrix \mathbf{G} . The
 94 covariance matrix of the estimates is approximated by the inverse of the information matrix,
 95 denoted as $\mathbf{H}(\boldsymbol{\theta})$. If the vector of estimates at convergence is $\hat{\boldsymbol{\theta}}$, then the distribution of $\hat{\boldsymbol{\theta}}$ is
 96 $N(\hat{\boldsymbol{\theta}}, \mathbf{H}(\hat{\boldsymbol{\theta}}))$.

97 REML estimates of covariances matrices are constrained to the parameter space, i.e.
 98 forced to have non-negative eigenvalues throughout so that they are positive semi-definite. Most
 99 REML software enforces this by re-parameterizing to estimate the elements of the Cholesky
 100 factors of covariance matrices, the elements of the lower triangular matrix \mathbf{L} for $\mathbf{G} = \mathbf{L}\mathbf{L}'$. In
 101 addition, positive diagonal elements of \mathbf{L} are ensured by transforming them to logarithmic scale
 102 (Meyer & Smith, 1996). On completion of the analysis, a 'valid' estimate of \mathbf{G} is obtained by
 103 reversing the transformation. Asymptotic normality of $\hat{\boldsymbol{\theta}}$ holds on either scale.

104 This then presents the possibility of using the multivariate normal sampling approach on
 105 two different scales; on the G-scale we can use multivariate normality to directly sample the
 106 elements of \mathbf{G} (with vector of estimates $\boldsymbol{\theta}_G$), while on the L-scale we can sample the elements of
 107 \mathbf{L} (with vector of estimates $\boldsymbol{\theta}_L$), and use those to construct estimates of \mathbf{G} . More formally, we

108 can generate \mathbf{G} matrix values, denoted $\hat{\mathbf{G}}$, drawn from the sampling distribution of \mathbf{G} , denoted
 109 $\tilde{\mathbf{G}}$, by sampling the elements of $\hat{\mathbf{G}}$, or by sampling the elements of $\hat{\mathbf{L}}$.

110 Sampling $\theta_{\mathbf{G}}$ directly attempts to approximate the large sample distribution of \mathbf{G} , similar
 111 to what MCMC typically does, albeit for different distributions. There is, however, a key
 112 difference between G-sampling and MCMC in that sampling on the G-scale does not guarantee
 113 that samples $\hat{\mathbf{G}}$ are positive semi-definite, i.e. we may obtain values outside of the parameter
 114 space, especially for matrices with eigenvalues close to the boundary. In contrast, MCMC
 115 algorithms typically sample a sum-of-squares and cross-products matrix guaranteed to be
 116 positive definite. Sampling on the G-scale will yield a mean of the $\tilde{\mathbf{G}}$ across samples equal to
 117 the REML estimate $\hat{\mathbf{G}}$. For linear functions of \mathbf{G} , sampling errors and confidence intervals
 118 derived are equivalent to those obtained from $\mathbf{H}(\hat{\theta}_{\mathbf{G}})$. For non-linear functions, we are likely to
 119 obtain slightly more appropriate estimates than with the Delta method, as we are not performing
 120 a linear approximation.

121 In contrast, sampling $\theta_{\mathbf{L}}$ mimics what is done during the REML estimation process and
 122 thus attempts to approximate the actual distribution of estimates of $\hat{\mathbf{G}}$. This is affected by
 123 constraints on the parameter space and, while it ensures positive semi-definite samples $\tilde{\mathbf{G}}$, their
 124 mean is thus not necessarily equal to $\hat{\mathbf{G}}$, the difference reflecting bias due to constraints. This
 125 bias can be substantial if sample sizes are small and k is reasonably large. Samples of $\tilde{\mathbf{G}}$ or its
 126 functions obtained by sampling $\theta_{\mathbf{L}}$ should thus be more comparable to those from the MCMC
 127 methods discussed above, which also constrain estimates to the parameter space.

128 On either the \mathbf{L} or \mathbf{G} scale, samples from the distribution $\tilde{\mathbf{G}}$ are obtained as

129
$$\tilde{\theta} = \hat{\theta} + \mathbf{L}_H \mathbf{d}$$

130 where \mathbf{L}_H is the Cholesky factor of the inverse of the information matrix, and \mathbf{d} is a vector of
131 standard normal deviates $d_i \sim N(0,1)$. The vector $\tilde{\boldsymbol{\theta}}$ is then reshaped into a sample matrix $\tilde{\mathbf{G}}$
132 for analysis. This approach has been implemented in the freely available mixed-model package
133 Wombat (Meyer, 2010-2015). Using simulated data, Meyer and Houle (2013) demonstrated
134 excellent agreement between empirical estimates of sampling variation and the L-scale REML-
135 MVN estimates, a point we return to in the Discussion.

136

137 **Methods**

138 We estimated the \mathbf{G} matrix based on wing measurements of a wild-collected population of *D.*
139 *melanogaster* from Wabasso, Florida USA (Mezey & Houle, 2005). Mezey and Houle generated
140 170 half-sib and 790 full-sib families and measured 17,323 wings from parents and offspring.
141 The phenotypic data were the x,y coordinates of 12 vein intersections measured with
142 WINGMACHINE, a semi-automated system that records scale information and detects vein
143 positions from digital wing images (Houle et al., 2003). The 24 coordinates obtained from each
144 wing were geometrically aligned to the mean shape using Procrustes least-squares
145 superimposition (Rohlf & Slice, 1990), which removes centroid size as a scaling factor.
146 Although the superimposed data are still in the form of 12 pairs of coordinates, 4 degrees of
147 freedom are used for superimposition, so the resulting \mathbf{G} matrix has a maximum rank or
148 dimensionality of 20. Mezey & Houle (2005) estimated \mathbf{G} piecewise using a method-of-
149 moments mixed model analyses of each pair of traits. Hansen and Houle (2008) used the
150 average of Mezey & Houle's male and female \mathbf{G} matrices, shown in Table S1. We will refer to
151 this as the H&H08 \mathbf{G} .

152 To estimate sampling error using REML-MVN, we re-estimated \mathbf{G} using REML
153 implemented in Wombat (Meyer, 2010-2015). Before the new analyses, the original Wabasso
154 data were geometrically aligned with a much larger set of 83,000 wings, including specimens
155 from 117 dipteran species, our spontaneous mutation data (Houle and Fierst 2013), and 184
156 *Drosophila* Genome Reference Project (Mackay et al., 2012) inbred lines. This enables as yet
157 unpublished comparisons of the Wabasso \mathbf{G} matrix to these data sets. We refer to the original
158 superimposition used in previous publications (Mezey & Houle, 2005, Hansen & Houle, 2008)
159 as the ‘Wabasso’ superimposition, and the new one as the ‘combined’ superimposition. Before
160 analysis, we scored wing data on the first 20 eigenvectors of the phenotypic variance-covariance
161 matrix from the pooled male and female Wabasso population data. We fit sex as a fixed effect to
162 obtain a direct estimate of the pooled-sex \mathbf{G} matrix. Estimation of \mathbf{G} was carried out for both
163 full- and reduced-rank models (Kirkpatrick & Meyer, 2004, Meyer & Kirkpatrick, 2005, 2008),
164 and we selected the best-fitting model on the basis of Akaike’s information criterion corrected
165 for small sample size (AICc). REML-MVN estimates of sampling variances were then obtained
166 drawing 100,000 samples of \mathbf{G} on both the G- and L-scale.

167 MCMC analyses were carried out in the R package MCMCglmm (Hadfield, 2010). To
168 investigate convergence, we initiated runs using parameters that were functions of the sex-
169 adjusted phenotypic covariance matrix. All runs used a degree of belief of 20.002, slightly more
170 than the dimensions of each matrix, and parameter expansion with a half-Cauchy prior with a
171 scale parameter of $\sqrt{1000}$. These values combine to establish the priors as minimally
172 informative. With parameter expansion, convergence was rapid, and burn-ins of just 100
173 iterations were necessary. Thinning to 60 iterations reduced autocorrelations between samples to
174 0.1 or less. Without parameter expansion, runs with different priors needed approximately 5,000

175 iterations of burn-in to achieve a stationary distribution, and runs with starting parameters far
 176 from the REML estimates often did not converge.

177 To provide a meaningful baseline against which to compare the parameter means and
 178 variances we carried out a parametric bootstrap analysis. This involved resampling data from a
 179 multivariate normal distribution on the pedigree of the Wabasso experiment, using the REML
 180 estimates of \mathbf{G} and residual variances as population parameters. A full REML analysis was then
 181 carried out for each of 1000 simulated data sets, and estimates of sampling variances were
 182 obtained as empirical variances across replicates. Both resampling and analysis were carried out
 183 in Wombat.

184 We used the mean wing shapes of seven other drosophilid species (listed in Tables 2 and
 185 3) to choose interesting directions in which to investigate evolvability (Hansen & Houle, 2008).
 186 The mean of each species was based on approximately 200 wings obtained from lab-reared flies.
 187 We recalculated the directions from *D. melanogaster* based on the same specimens used in
 188 H&H08, but using the combined superimposition, instead of a species-data only superimposition.
 189 This resulted in slightly different estimates of phenotypic distance and direction from those
 190 shown in H&H08.

191 Evolvability, e , is the predicted response to unit strength selection in the direction of the
 192 selection gradient, $\boldsymbol{\beta}$, in the absence of stabilizing selection. It is calculated as the projection of
 193 the response vector to a unit-length $\boldsymbol{\beta}$ on $\boldsymbol{\beta}$

$$194 \quad e(\boldsymbol{\beta}) \equiv \boldsymbol{\beta}'\mathbf{G}\boldsymbol{\beta}$$

195 Conditional evolvability, c , is the response to unit strength selection when stabilizing selection
 196 around the selected direction is infinitely strong. Conditional evolvability is

$$197 \quad c(\boldsymbol{\beta}) = (\boldsymbol{\beta}'\mathbf{G}^{-1}\boldsymbol{\beta})^{-1} \boldsymbol{\beta}'\boldsymbol{\beta},$$

198 and gives the response in direction β to a unit-length β when the response is constrained to be in
199 direction β . The actual response to selection in direction β will be between $e(\beta)$ and $c(\beta)$, falling
200 closer to $e(\beta)$ when stabilizing selection in other directions is weak. Autonomy, a , is the ratio
201 c/e , and captures the proportion of variation that allows response in the direction of a selection
202 gradient. These measures of evolvability are informative when the units in which traits are
203 measured are the same (as in our wing shape data), or the traits have been standardized in the
204 same manner.

205 When the direction of selection is not predictable, one can ask about the average
206 evolvability of a population averaged over all possible directions. Hansen and Houle (2008)
207 showed that the expected evolvability, \bar{e} , is the average eigenvalue of the \mathbf{G} matrix. No exact
208 solution is available for the expected conditional evolvability, \bar{c} , or the expected autonomy, \bar{a} ,
209 but good approximations have been derived in Hansen & Houle (2008, 2009). The corrected
210 formulas for these are repeated in Appendix 1.

211

212

213 **Results**

214 Reanalysis of Mezey & Houle's (2005) data on wing shape in the Wabasso population of
215 *Drosophila melanogaster* shows that the best estimate is a \mathbf{G} of rank 20 (full-rank). The full
216 model is superior by 38 AIC-penalized log-likelihood units to the simplified rank 19 model in
217 both the Wabasso and combined superimpositions. Mezey & Houle's (2005) conclusion that
218 there were at least 18 dimensions of genetic variation in these data was conservative. The
219 REML estimate of \mathbf{G} , back-projected into the original 24 dimensions is shown in Table S2.

220 Table 1 shows the values of a set of evolvability statistics (Hansen & Houle, 2008, see
221 Methods for definitions) and their sampling errors from parametric bootstrapping, MCMC
222 estimation and the REML-MVN method. In addition estimates for the \mathbf{G} estimated by Hansen &
223 Houle (2008) are also shown for comparison. Overall, the sampling standard deviations are quite
224 small relative to their means, resulting in sampling coefficients of variation for the evolvability
225 statistics of 5% or less, with the exception of the minimum eigenvalue, e_{min} , which has a CV
226 greater than 10% by all methods. The minimum eigenvalue is the most difficult to estimate as it
227 is the variance closest to a boundary value of 0. G-scale estimates are not constrained to have a
228 non-negative e_{min} , so the fact that the G-scale estimates of e_{min} are still many standard deviations
229 greater than 0 supports the finding of a full-rank \mathbf{G} matrix. The sampling distributions of all
230 statistics were approximately normal (results not shown).

231 The parametric bootstrap estimates are a suitable baseline to compare the other methods
232 with, as that method enforces multivariate normal data, and makes no large-sample assumption.
233 The mean REML and MCMC estimates are all within a small fraction of the sampling standard
234 deviation of the parametric bootstrap value, suggesting that there is little bias in the mean
235 estimates of the parameters. On the other hand, the H&H08 estimates of \bar{e} and e_{max} are more than
236 4 standard deviations higher than the REML estimates. Conversely, the H&H08 \bar{c} and e_{min} are
237 about 2 standard deviations lower than the REML estimates. The larger eigenvalues in the
238 H&H08 estimate are biased upwards, while the smaller eigenvalues are biased downwards.
239 Systematic over-dispersion of sample eigenvalues is a well-known outcome for estimates that are
240 not constrained to the parameter space (Hill & Thompson, 1978).

241 Closer examination shows that the estimates of mean and sampling variation may show
242 subtle biases. Even though the parametric bootstrap was initiated with the REML estimate, the

243 estimates recovered from the bootstrap do not match the ‘best’ REML’ estimate precisely. In
244 particular, the three statistics that depend on the inverse of \mathbf{G} and therefore on the smallest
245 eigenvalues (e_{min} , \bar{c} , \bar{a}), are all more than a standard deviation lower in the bootstrap sample.
246 This may indicate departures of the data from multivariate normality in the original data. The
247 same three statistics have slightly higher means in the L-scale sample than in the G-scale sample,
248 which is consistent with the L-scale constraint towards positive-definite matrices. For these data,
249 sampling on the G-scale, θ_G , did not yield any samples which were not positive definite, and no
250 values of e_{min} based on sampling the elements of its Cholesky factor, θ_L approached the arbitrary
251 constrained value of 0.0001 in Wombat. This leaves the precise cause of the discrepancy
252 somewhat unclear.

253 To get a broader sense for the similarity of the estimates, we calculated the mean and
254 standard deviation of a range eigenvalues, with the results shown in Figure 1. On the log scale
255 all four sets of mean estimates are quite similar, with differences only becoming apparent in the
256 smallest eigenvalues. Sampling standard deviations are systematically lower in the REML
257 estimates compared to the bootstrap; MCMC standard deviations are even lower. This may
258 suggest a small bias in the REML-MVN error estimates, as they are asymptotic, lower bound
259 values. While the Wabasso data set comprises a large number of records, a 20-variate, full rank
260 REML analysis requires estimation of 420 covariance components. Larger estimates from the
261 parametric bootstrap may thus indicate that the sample size is not quite sufficient for large
262 sample theory to hold. This pattern is sometimes reversed for the smallest eigenvalues and the
263 statistics that depend on \mathbf{G}^{-1} . This may be due to the fact that the REML constraints on the
264 parameter space will tend to truncate the smallest eigenvalues (Amemiya, 1985). An alternative

265 explanation for these exceptions is sampling error, as the precision of the error estimates for
266 these statistics is relatively low.

267 Schluter (1996) found that among-species and among-population variation tended to lie
268 close to the first eigenvector of \mathbf{G} , \mathbf{g}_{max} . Hansen and Houle (2008- H&H08) reasoned that if \mathbf{G}
269 shapes among-species differences, then the differences among species should be in those aspects
270 of variation that have the highest evolvabilities, even if those are very different from \mathbf{g}_{max} . To
271 choose interesting directions of selection to investigate, Hansen and Houle (2008) took
272 *Drosophila melanogaster* as the focal species and predicted the ability of *D. melanogaster* to
273 evolve towards the phenotype of seven other species that span the traditional genus *Drosophila*
274 and one closely related outgroup (*Scaptodrosophila latifasciaeformis*). The results are shown in
275 Table 2 for evolvability and Table 3 for conditional evolvability.

276 As originally found with the H&H08 \mathbf{G} , evolvabilities and conditional evolvabilities in
277 the directions of these species are all in the more variable parts of the phenotype space. As a
278 result, most of the estimates in H&H08 are substantial overestimates, consistent with the bias in
279 the higher eigenvalues of \mathbf{G} noted above.

280 Estimates of sampling error for the evolvabilities estimated with each method are again
281 broadly similar, consistent with the results noted above. The estimates are fairly precise, with
282 sampling coefficients of variation slightly less than 5% for the evolvabilities, and 6 to 15% for
283 the conditional evolvabilities. These errors are sufficiently small that almost all differences in
284 evolvabilities between species are statistically significant.

285

286 **Discussion**

287 It has long been known that the additive genetic variance-covariance \mathbf{G} is a useful tool for
288 making predictions about evolution, and for interpreting the pattern of diversification among taxa
289 (Lande, 1979). Until recently, efforts to utilize these results have been hampered by the
290 difficulty of assessing the sampling variation of \mathbf{G} and of the complex and often non-linear
291 statistics that are functions of \mathbf{G} . Bayesian estimation using a Markov-chain Monte Carlo
292 algorithm (MCMC) has recently been applied to such problems (e.g., O'Hara et al., 2008,
293 Hadfield, 2010, Aguirre et al., 2014, Stinchcombe et al., 2014), but application of MCMC
294 methods can be computationally intensive for large problems.

295 As an alternative, we have applied our recently implemented REML-MVN method
296 Meyer & Houle, 2013) of estimating the sampling variation in restricted maximum likelihood
297 (REML) estimates of additive genetic variance-covariance matrices. As our example, we used
298 data on wing shape in *Drosophila melanogaster* from a very large experiment (Mezey & Houle
299 2005). We focused on sampling variation in the evolvability statistics proposed in Hansen &
300 Houle (2008).

301 Our goal in this contribution has been first to demonstrate the REML-MVN approach for
302 a single-well-estimated data set. Comparison of parameter estimates and their sampling error
303 based shows that REML-MVN estimates are quite similar to those derived from the parametric
304 bootstrapping and MCMC in mean and variance. We can use the parametric bootstrap as the
305 baseline for comparison, as those results depend on simulated data that corresponds to the
306 assumptions of the analysis. The similarity of all three sets of results validates the accuracy both
307 the parameter estimates and their sampling errors from the REML-MVN and MCMC

308 approaches. This validation of the REML-MVN approach is also supported by the results for
309 simulated data reported by Meyer & Houle (2013).

310 Looking more closely, there are small quantitative departures between bootstrap, REML-
311 MVN and MCMC estimates. Discrepancies could in principle be explained either by flaws in
312 the methods, in their application, or by departures of the data from the assumed multivariate
313 normal distribution. In the case of REML-MVN, these departures potentially reflect
314 insufficiently sampled aspects of \mathbf{G} for which large sample results do not hold.

315 Given these results, the REML-MVN approach is attractive because it is usually
316 computationally much more efficient than either MCMC, or bootstrap approaches. For the data
317 reanalyzed here, convergence in Wombat (Meyer, 2007, Meyer, 2010-2015) from a poor initial
318 estimate of \mathbf{G} (equal to half the phenotypic variance-covariance matrix) takes 9.5 hours on an
319 AMD Opteron 4180 processor with speed of 2793 MHz. Generation of 100,000 REML-MVN
320 samples then requires only seconds of processor time. Using the R package MCMCglmm
321 (Hadfield, 2010) the same problem takes about 6.5 hours to produce 1000 iterations. Thinning to
322 every 60 generations, production of the 1,000 samples used in this analysis took over 400 hours
323 of processor time. The greater the number of variables, and the closer the initial estimates are to
324 the final estimate, the greater the run time advantage of REML-MVN over MCMC.

325 A second advantage of a maximum likelihood approach is that it can be used to test
326 whether fitting a complex model over a simpler one is supported by the data (Meyer &
327 Kirkpatrick, 2005, Meyer & Kirkpatrick, 2008). Such tests are important to perform when there
328 is some doubt about whether a complex model can be supported by the data, given that both
329 standard MCMC and the L-scale REML-MVN approach produce estimates constrained to be of
330 full rank.

331 While our results, plus the simulations reported in Meyer & Houle (2013), validate the
332 use of REML-MVN in some cases, this does not mean that REML-MVN will perform well for
333 all data sets. Therefore, we suggest that REML-MVN estimates of sampling error should
334 continue to be validated with estimates from a second approach. Parametric bootstrapping based
335 on the REML estimates obtained is probably the least computationally intensive of the
336 alternatives, given that if the model is strongly supported by the data, convergence with a new
337 simulated data set should be relatively rapid. Restricted maximum likelihood does well for
338 multivariate normal data, but is unsuitable when the data follows other distributions, whereas
339 Bayesian methods readily accommodate such cases. REML-MVN depends on large-sample
340 approximations that are inappropriate for data sets where the amount of information in the data is
341 small relative to the number of parameters estimated. For such cases MCMC is likely to perform
342 better. Alternative approaches, based for example on the profile likelihood for individual
343 parameters, might also be more appropriate than REML-MVN when large sample properties do
344 not hold.

345 The REML reanalysis of these data confirmed Mezey & Houle's (2005) conclusion that
346 the \mathbf{G} matrix for this data set is full-rank. Models with lower dimensionality fit at least 38
347 Akaike information criterion units less well than the full 20-dimensional model. Hine & Blows
348 (2006) suggested that the bootstrapping method employed by Mezey & Houle (2005) was biased
349 towards high dimensionality, but Hine & Blows simulated only one of the two bootstrapping
350 approaches of Mezey & Houle. On the other hand, these new analyses do show that the original
351 estimates obtained by Mezey & Houle (2005), using a method of moments analysis, were biased.
352 Results that depend on the best-estimated parts of the \mathbf{G} with large additive genetic variances,
353 such as the maximum evolvability and the average evolvability were overestimated by Mezey &

354 Houle (2005) by up to 17%. On the other hand, the less well-estimated aspects of the matrix that
355 have the least genetic variance were underestimated by up to 8%. This pattern of bias is
356 expected for unconstrained estimates of covariance matrices (Hill & Thompson, 1978).

357 In conclusion, resampling \mathbf{G} matrices using the restricted maximum likelihood,
358 multivariate normal approach can generate accurate assessments of sampling variation in
359 evolutionary statistics. The relatively short run time of this method makes it an attractive
360 alternative to both data resampling and Bayesian estimation using a Markov chain Monte Carlo
361 approach.

362

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- 1 Table 1. Overall evolvability statistics. Evolvabilities and conditional evolvabilities have units of 10^6 centroid size. Bootstrap, REML
 2 resamples and MCMC posterior distributions are each calculated from 1,000 samples.

	Mean					Standard deviation				
	\bar{e}	e_{max}	e_{min}	\bar{c}	\bar{a}	\bar{e}	e_{max}	e_{min}	\bar{c}	\bar{a}
H&H08	14.61	83.04	0.09	1.00	0.069					
REML	13.071	70.870	0.129	1.076	0.0947					
Parametric bootstrap	13.081	71.652	0.109	1.000	0.0883	0.247	3.247	0.016	0.049	0.0045
REML-MVN, G-scale	13.083	71.527	0.109	1.001	0.0883	0.222	2.834	0.018	0.055	0.0049
REML-MVN, L-scale	13.121	71.418	0.122	1.067	0.0937	0.227	2.822	0.017	0.049	0.0044
MCMC	13.259	72.168	0.110	1.022	0.0888	0.211	2.558	0.015	0.050	0.0044

- 1 Table 2. Evolvabilities in the direction of species divergence, $e(\beta)$, in units of centroid size $\times 10^6$. Phenotypic distances from *D.*
 2 *melanogaster* wings to other Drosophilid flies are in centroid size units.

Species	distance											
	to D.	Best estimate			Mean				Standard deviation			
	<i>melano-</i>				REML				REML			
	<i>gaster</i>	H&H08	REML	MCMC	bootstrap	L-scale	G-scale	MCMC	bootstrap	L-scale	G-scale	MCMC
<i>D. simulans</i>	0.011	34.4	22.52	22.22	22.50	22.55	22.59	23.08	1.11	1.00	0.98	0.92
<i>D.</i>												
<i>ananassae</i>	0.082	66.7	41.44	41.85	41.43	41.50	41.54	42.11	1.92	1.70	1.67	1.45
<i>D. pseudo-</i>												
<i>obscura</i>	0.041	64.9	38.44	38.50	38.47	38.46	38.40	38.99	1.79	1.64	1.57	1.59
<i>D.</i>												
<i>willistoni</i>	0.056	55.1	47.5	48.40	47.60	47.50	47.75	48.35	2.26	2.03	2.07	1.81
<i>D. virilis</i>	0.057	46.6	30.96	31.31	31.00	30.84	31.00	31.26	1.40	1.28	1.20	1.20
<i>D.</i>												
<i>grimshawi</i>	0.172	55.2	41.78	41.95	41.82	41.66	41.89	42.20	1.94	1.70	1.64	1.55
<i>S. latifasi-</i>												
<i>aeformis</i>	0.114	56.9	48.63	49.03	48.68	48.65	48.84	49.21	2.29	1.95	1.96	1.65

- 1 Table 3. Conditional evolvabilities in the direction of species divergence, $c(\beta)$, in units of centroid size $\times 10^6$. Samples described in
 2 Table 2.

Species	Best estimate			Mean				Standard deviation			
	H&H08	REML	MCMC	bootstrap	REML L-	REML G-	MCMC	REML L-	REML G-	MCMC	
					scale	scale		scale	scale		
<i>D. simulans</i>	2.7	1.69	1.50	1.57	1.66	1.58	1.50	0.17	0.17	0.18	0.16
<i>D. ananassae</i>	13.7	13.75	13.11	13.09	13.51	13.11	13.11	1.04	0.96	0.99	0.84
<i>D. pseudo-</i>											
<i>obscura</i>	12.7	6.69	6.51	6.28	6.58	6.30	6.51	0.56	0.54	0.59	0.57
<i>D. willistoni</i>	10.7	10.88	10.68	10.48	10.68	10.46	10.68	0.68	0.65	0.64	0.60
<i>D. virilis</i>	10.5	4.68	4.58	4.48	4.60	4.50	4.58	0.30	0.28	0.30	0.28
<i>D. grimshawi</i>	17.4	7.5	7.65	7.20	7.36	7.21	7.65	0.46	0.43	0.46	0.45
<i>S. latifasiae-</i>											
<i>formis</i>	24.9	9.53	8.24	8.75	9.37	8.75	8.24	1.15	1.19	1.24	1.08

4 Figure 1. Mean (A) and standard deviation (B) of \log_{10} eigenvalue estimates from the parametric
5 bootstrap, REML-MVN on the L- and G-scales, and MCMC.

6

7

8 **Appendix 1**

9

10 The original approximations for the expected conditional evolvability, \bar{c} , and autonomy, \bar{a} ,
 11 over all directions in phenotype space in Hansen & Houle (2008) were incorrect, and were
 12 corrected in Hansen & Houle (2009). For clarity, we repeat the corrected equations here.

13 The approximations depend on the following quantities: k is the dimension of matrix,
 14 $E[\lambda]$ and $E[1/\lambda]$ are the means of the eigenvalues and of the inverse eigenvalue, respectively,
 15 $H[\lambda] = 1/E[1/\lambda]$ is the harmonic mean eigenvalue; $I[\lambda] = \text{Var}(\lambda)/(E[\lambda]^2)$ is the variance of
 16 the eigenvalues, standardized by the square of the mean eigenvalue; $I[1/\lambda] = \text{Var}(1/\lambda)/(E[1/\lambda]^2)$
 17 is the variance of the inverse of the eigenvalues standardized by the square of the mean inverse
 18 eigenvalue.

19 The expected value of \bar{c} is approximately

$$20 \quad \bar{c} \approx H[\lambda] \left(1 + \frac{2I[1/\lambda]}{k+2} \right).$$

21 The expected value of \bar{a} is approximately

$$22 \quad \bar{a} \approx \frac{H[\lambda]}{E[\lambda]} \left(1 + 2 \frac{I[\lambda] + I[1/\lambda] - 1 + H[\lambda]/E[\lambda] + 2 I[\lambda] I[1/\lambda]/(k+2)}{k+2} \right).$$